

Nucleation of austenite in martensite

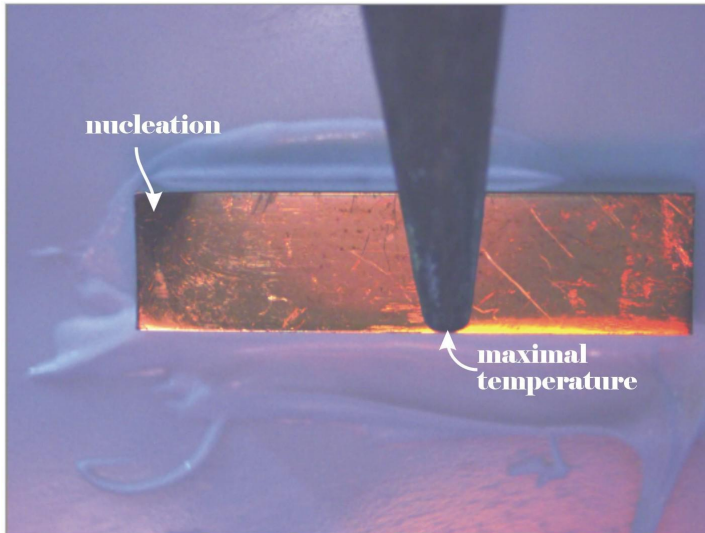
Konstantinos Koumatos

OxMOS,
Mathematical Institute, University of Oxford,
Supported by EPSRC

29/09/10

Experimental observations (H. Seiner)

- ▶ CuAlNi bar of dimension $12 \times 3 \times 3$ mm.
- ▶ Orientation at austenite close to $(1, 0, 0)$, $(0, 1, 0)$, $(0, 0, 1)$.
- ▶ Mechanically stabilised into a pure phase of martensite containing a single variant.



Austenite was nucleated via a localized heat source.

Irrespective of the point of contact, the austenite always nucleated at a corner.

Introduction

We will follow the nonlinear elasticity model for martensitic transformations in which microstructures are identified with minimizing sequences for some energy functional

$$\mathcal{E}(y) := \int_{\Omega} \varphi(Dy(x)) dx.$$

Any minimizing sequence of gradients Dy^j (assumed bounded in L^∞) will converge weak-* to some gradient Dy (up to a subsequence) which is the **macroscopic deformation gradient**.

However, in passing to this limit, a lot of information is lost and then, the use of gradient Young measures becomes a convenient way to describe microstructures.

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However, in passing to this limit, a lot of information is lost and then, the use of gradient Young measures becomes a convenient way to describe microstructures.

Any minimizing sequence of gradients, Dy^j , **generates** a family $\nu = (\nu_x)_{x \in \Omega}$ of probability measures such that for all continuous f

$$f(Dy^j) \xrightarrow{*} \langle \nu_x, f \rangle = \int_{M^{3 \times 3}} f(A) d\nu_x(A) \text{ in } L^\infty \quad (\text{up to a subsequence}).$$

The problem then becomes that of minimising

$$I(\nu) = \int_{\Omega} \langle \nu_x, \varphi \rangle dx$$

over the set of $(W^{1,\infty})$ gradient Young measures. Any minimizer ν of I is generated by a minimizing sequence Dy^j of \mathcal{E} (and vice versa) for which the macroscopic deformation gradient satisfies

$$Dy(x) = \bar{\nu}_x = \langle \nu_x, \text{id} \rangle.$$

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Our work is also connected to the problem of necessary and sufficient conditions for an extremal (solution to the Euler-Lagrange equations) to be a strong local minimizer for

$$\mathcal{E}(y) := \int_{\Omega} \varphi(x, y(x), Dy(x)) dx.$$

For the vectorial case and Ω smooth, known necessary conditions are:

- ▶ positivity of the second variation
- ▶ quasiconvexity in the interior (N.G. Meyers, '65)
- ▶ quasiconvexity at the boundary (J.M. Ball/J.E. Marsden, '84)

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In this work, we wish to make use of some notion of quasiconvexity to explain why the nucleation cannot occur in the **interior** or the **faces** and **edges**, as well as show how the austenite can compatibly nucleate from any **corner**.

For domains with edges and corners there are new associated quasiconvexity conditions.

Cubic-to-orthorhombic variants $\alpha, \beta, \gamma > 0$ and $\alpha \neq \gamma$

$$U_1 = \begin{pmatrix} \beta & 0 & 0 \\ 0 & \frac{\alpha+\gamma}{2} & \frac{\alpha-\gamma}{2} \\ 0 & \frac{\alpha-\gamma}{2} & \frac{\alpha+\gamma}{2} \end{pmatrix} \quad U_2 = \begin{pmatrix} \beta & 0 & 0 \\ 0 & \frac{\alpha+\gamma}{2} & \frac{\gamma-\alpha}{2} \\ 0 & \frac{\gamma-\alpha}{2} & \frac{\alpha+\gamma}{2} \end{pmatrix}$$

$$U_3 = \begin{pmatrix} \frac{\alpha+\gamma}{2} & 0 & \frac{\alpha-\gamma}{2} \\ 0 & \beta & 0 \\ \frac{\alpha-\gamma}{2} & 0 & \frac{\alpha+\gamma}{2} \end{pmatrix} \quad U_4 = \begin{pmatrix} \frac{\alpha+\gamma}{2} & 0 & \frac{\gamma-\alpha}{2} \\ 0 & \beta & 0 \\ \frac{\gamma-\alpha}{2} & 0 & \frac{\alpha+\gamma}{2} \end{pmatrix}$$

$$U_5 = \begin{pmatrix} \frac{\alpha+\gamma}{2} & \frac{\alpha-\gamma}{2} & 0 \\ \frac{\alpha-\gamma}{2} & \frac{\alpha+\gamma}{2} & 0 \\ 0 & 0 & \beta \end{pmatrix} \quad U_6 = \begin{pmatrix} \frac{\alpha+\gamma}{2} & \frac{\gamma-\alpha}{2} & 0 \\ \frac{\gamma-\alpha}{2} & \frac{\alpha+\gamma}{2} & 0 \\ 0 & 0 & \beta \end{pmatrix}$$

Setting up the problem

Let Ω be a bounded domain describing the CuAlNi bar at the austenite and assume that $\theta > \theta_c$. We wish to minimise

$$I(\nu) = \int_{\Omega} \langle \nu_x, W \rangle dx,$$

where

$$W(F) = \begin{cases} -\delta, & F \in SO(3) \\ 0, & F \in \bigcup_{i=1}^6 SO(3) U_i \\ +\infty, & \text{otherwise.} \end{cases}$$

This functional is derived via the means of Γ -convergence and is used to make the problem more tractable.

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If we let $K := SO(3) \cup \bigcup_{i=1}^6 SO(3) U_i$ and

$$\nu_x(SO(3)) = \int_{SO(3)} d\nu_x(A) \text{ -the volume fraction of austenite at } x \in \Omega,$$

then, equivalently,

$$I(\nu) = \begin{cases} -\delta \int_{\Omega} \nu_x(SO(3)) dx, & \text{supp } \nu \subset K \\ +\infty, & \text{otherwise.} \end{cases}$$

Letting U_s denote the mechanically stabilized martensitic variant, the homogeneous gradient Young measure

$$\nu = \delta_{U_s}$$

will correspond to a pure phase of U_s .

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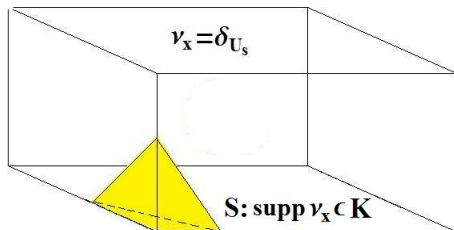
Let $S \subset \Omega$ be a region where the nucleation will be allowed to take place.

We perturb δU_s in this region and we let $\nu = (\nu_x)_{x \in \Omega}$ be a gradient Young measure such that

$$\begin{aligned}\nu_x &= \delta U_s, & x &\notin S \\ \text{supp } \nu &\subset K, & x &\in S.\end{aligned}$$

Corner

S (yellow region) has parts of the three faces that meet at the given corner as a free boundary.



Aim: $\exists \nu_x$ as above such that

$$I(\nu) < I(\delta U_s) = 0 \left(\iff \int_{\Omega} \nu_x(SO(3)) > 0 \right).$$

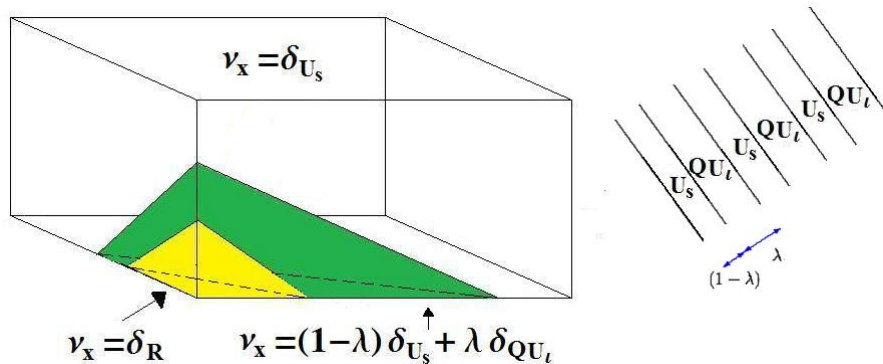
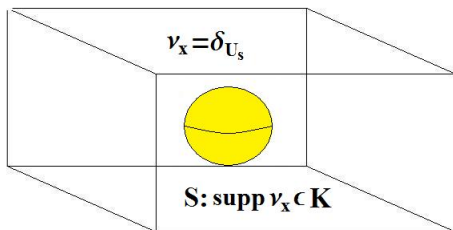


Figure: Nucleation from a corner; Yellow region occupied by austenite and green region by a simple laminate of martensite containing U_s .

Interior

S (yellow region) with no free boundary.



Aim: $\forall \nu_x$ as above

$$I(\nu) \geq I(\delta_{U_s}) = 0 \left(\iff \int_{\Omega} \nu_x(SO(3)) = 0 \right).$$

Definition

A function $W : M^{3 \times 3} \rightarrow \mathbb{R} \cup \{+\infty\}$ is **quasiconvex** at $F \in M^{3 \times 3}$ if for any **homogeneous** gradient Young measure μ with $\bar{\mu} = F$,

$$W(F) \leq \langle \mu, W \rangle.$$

Lemma

If the energy density W is quasiconvex at U_s then $I(\nu) \geq I(\delta_{U_s})$ so that nucleation cannot occur in the interior.

Remark: Using the minors' relations one can show that

$$\bar{\mu}_x = U_s \implies \mu_x(SO(3)) = 0.$$

Here, this implies that W is quasiconvex at U_s so that, from the lemma above, nucleation cannot occur in the interior.

Nevertheless, the same result will be used for faces and edges.

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Faces and Edges

For a face, we perturb δ_{U_s} in a region $S \subset \Omega$ with part of one face as a free boundary.

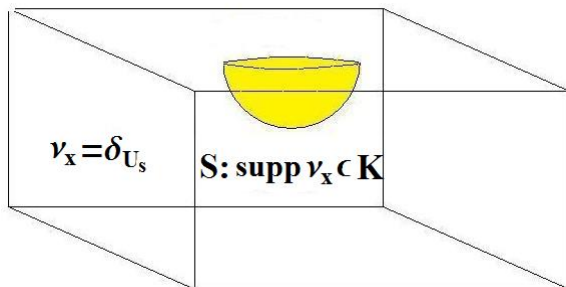


Figure: Nucleation from a face; region S in yellow.

For an edge, the set $S \subset \Omega$ where δ_{U_s} is perturbed has parts of two faces as a free boundary.

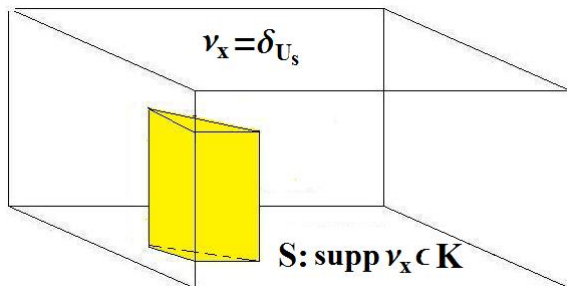


Figure: Nucleation from an edge; region S in yellow.

Both for the faces and edges, we wish to show that for all gradient Young measures as in the respective pictures,

$$I(\nu) \geq I(\delta_{U_s}).$$

(quasiconvexity at a face and an edge respectively)

To proceed we need a definition.

Definition

A vector $e \in S^2$ is called a **maximal direction** for U_s if

$$|U_s e| = \max_i \{1, |U_i e|\}.$$

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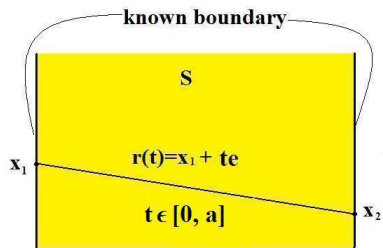
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$$\bar{v}_x = Dy(x)$$

Figure: $r(t) \subset S$.

If e is a maximal direction for U_s

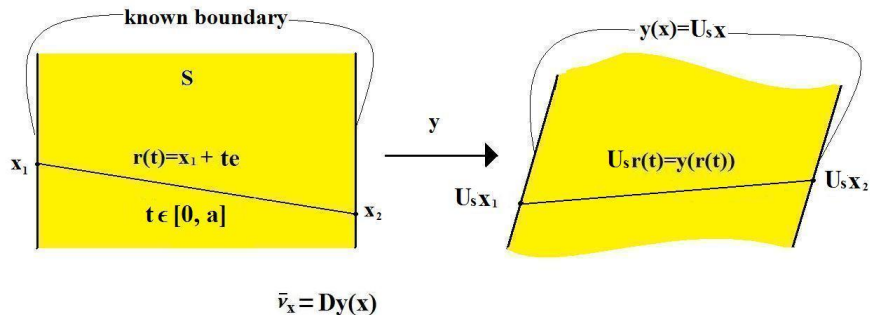


Figure: Necessary deformation of $r(t) \subset S$ under y

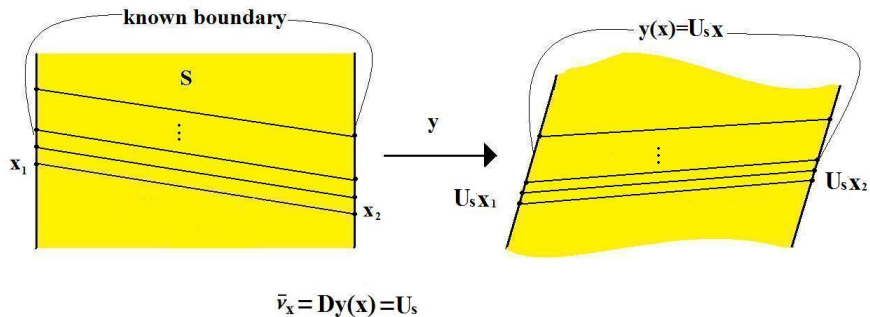
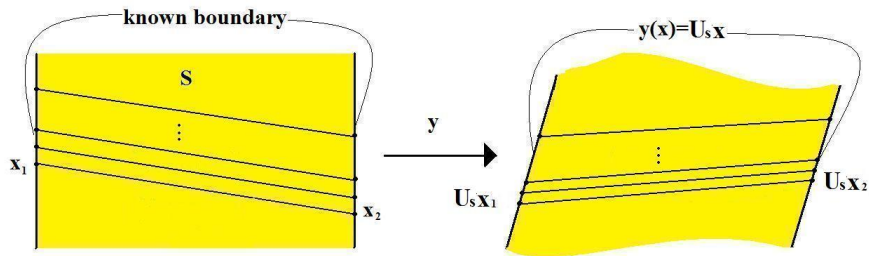


Figure: Necessary deformation of $r(t) \subset S$ under y



$$\bar{v}_x = Dy(x) = U_s \implies I(v) \geq I(\delta_{U_s}) \quad \text{using the same argument as for the interior}$$

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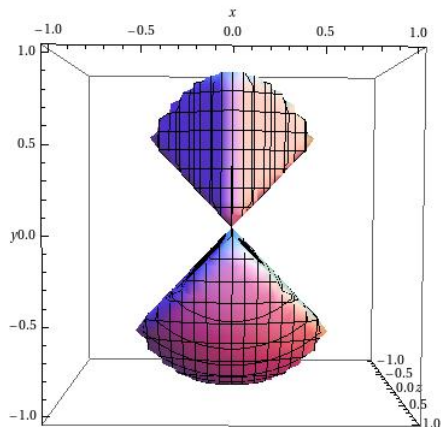


Figure: Set of maximal directions for U_1 .

Adding new directions

Although these directions can cover some domains, they are not enough to cover the specimen used in the experiment.

For this reason, we develop a method similar to the above and add more directions using the inverse transformation.

For this, we need another definition.

Definition

A vector $e \in S^2$ is a **maximal direction** for U_s^{-1} if

$$|\operatorname{cof} U_s e| = \max_i \{1, |\operatorname{cof} U_i e|\}.$$

For the method to be applicable we need to employ the non-linear elasticity framework of **Ciarlet and Nečas** by adding a constraint on the admissible deformations. This is

$$\int_{\Omega} \det Dy(x) \, dx \leq \text{vol } y(\Omega)$$

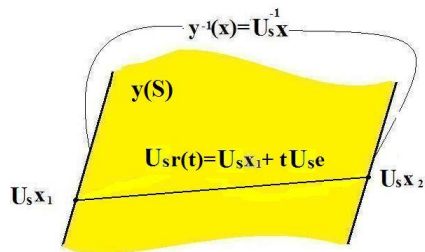
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and ensures the a.e. injectivity of the minimisers.

Using injectivity a.e. along with other results, we can improve the regularity to ensure that the minimiser is bi-Lipschitz and that (roughly speaking) the boundary of the image of S , $y(S)$, does not come into contact with itself.



$$\bar{v}_x = Dy(x)$$

Figure: $U_{sr}(t) \subset y(S)$.

If $U_s e$ is a maximal direction for U_s^{-1}

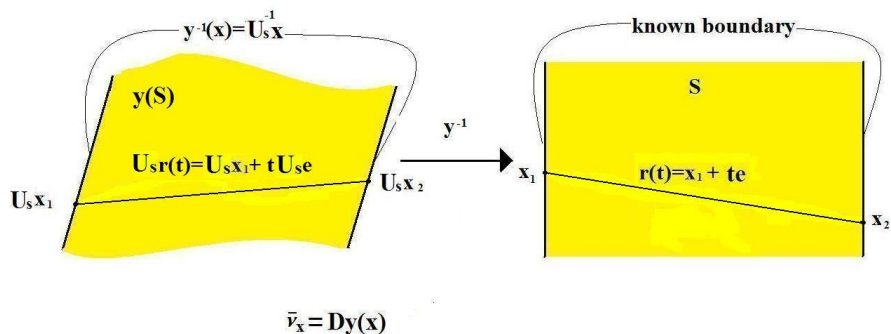
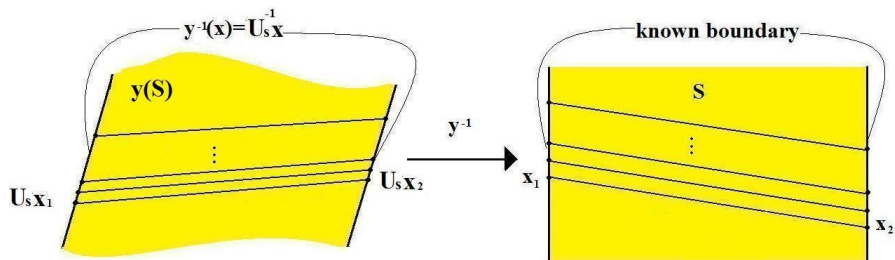


Figure: Necessary deformation of $U_s r(t) \subset y(S)$ under y^{-1}



$$\bar{v}_x = Dy(x) = U_s \implies I(v) \geq I(\delta_{U_s}) \quad \text{using the same argument}$$

Figure: Necessary deformation of $U_s r(t) \subset y(S)$ under y^{-1}

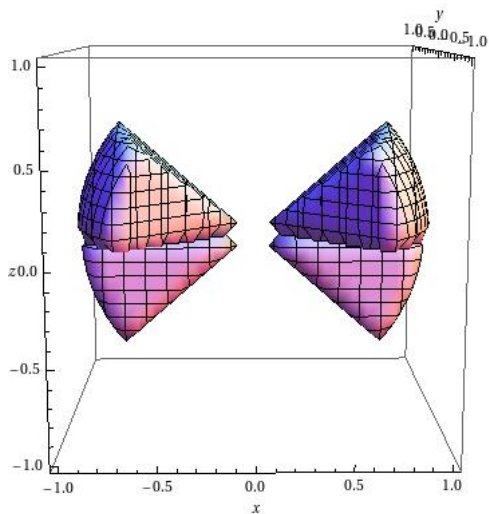


Figure: Vectors e such that $U_1 e$ is a maximal direction for U_1^{-1} .

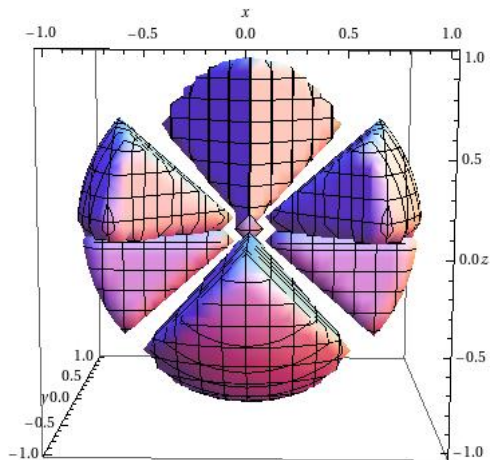


Figure: All vectors e with e maximal for U_1 or $U_1 e$ maximal for U_1^{-1} .

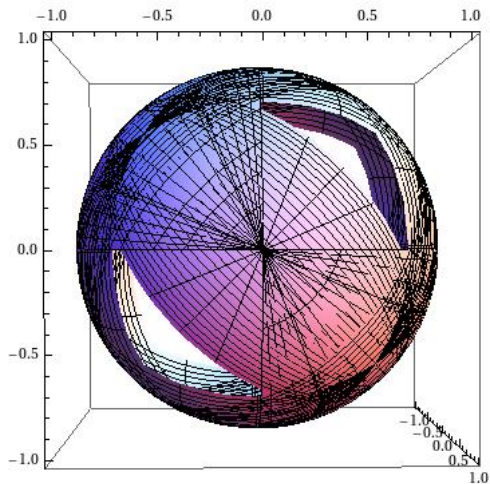


Figure: Normals to all possible faces the method can cover.

Conclusion

For the specimen in H. Seiner's experiment and for any U_s we can cover the entire domain and conclude that, indeed, the nucleation can only occur at a corner.

Moreover, for each $s = 1, \dots, 6$ the sets of maximal directions for U_s and U_s^{-1} (as well as their union) contain sets of three linearly independent vectors.

This means that for any parallelepiped with edges parallel to these directions, nucleation can only be initiated at a corner making the method applicable to several other domains.

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